Effective Boundary Conditions for the Heat Equation with Three-dimensional Anisotropic and Optimally Aligned Coatings

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2 History

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- **5** Boundary Coating
- 6 Ongoing Work

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Motivations : cell



Figure: E. coli cell; membrane thick and diameter ratio 1:500; red-headed molecules are phospholipids

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Coatings may be Anisotropic : anisotropy for TBC is caused by the fashions in which the ceramic "YSZ"(yttria-stabilized zirconia) is deposited on the blade :

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TBC

If YSZ is sprayed on by electron beam physical vapor deposition (EB-PVD) method, then parallel crystal columns that are perpendicular to the boundary form; and between these columns a small volume fraction of elongated pores also form. (Picture taken from J.R. Nicholls K.J. Lawson, A. Johnstone, D.S. Rickerby)



Common features :

- Domain contains a thin component;
- Diffusion tensors on different components are drastically different. Issues :
 - The multi-scale in size and different diffusion tensors lead to computational difficulty;
 - It is hard to see the effect of the thin component;

Resolution :

• Think of the thin component as widthless surface and impose "effective boundary conditions" (EBCs).

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- As early as 1959, Carlaw and Jaeger, in their classic book *Conduction of Heat in Solids*, first derived EBCs formally;
- Rigorous derivation was initiated by Sanchez-Palencia in 1974, to study Laplace equation and the heat equation with thin diamond-shaped inclusions;
- In 1980, Brezis, Caffarelli and Friedman studied the case of Poisson equation;
- In 1987, Buttazo and Kohn studied the case of thin layer of oscillating thickness;
- Lots of follow-up work on elastic equations, electromagnetic equations, etc;

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Mathematical model



Fig. 1. The domain $\Omega = \overline{\Omega}_1 \cup \Omega_2 \subset \mathbb{R}^N$ consists of an isotropic body Ω_1 surrounded by a layer Ω_2 of uniform thickness δ

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Mathematical model

For any fixed T > 0,

$$\begin{cases} u_t - \nabla \cdot (A(x)\nabla u) = f(x,t), & (x,t) \in Q_T = \Omega \times (0,T), \\ u = 0, & (x,t) \in S_T = \partial \Omega \times (0,T), \\ u = u_0, & (x,t) \in \Omega \times \{0\} \end{cases}$$
(1)

where Ω_1 is fixed, $u_0 \in L^2(\Omega)$ and $f \in L^2(Q_T)$. A(x) is given by

$$A(x) = \begin{cases} kI_{N \times N}, & x \in \Omega_1\\ (a_{ij}(x))_{N \times N}, & x \in \Omega_2 \end{cases}$$
(2)

where k is a positive constant and $(a_{ij})_{N \times N}$ is positive-definite. Moreover, u satisfies

$$u_1 = u_2, \ k \frac{\partial u_1}{\partial \mathbf{n}} = A(x) \nabla u_2 \cdot \mathbf{n} \quad \text{on} \quad \partial \Omega_1,$$

where $\mathbf{n} = (n_1, ..., n_N)$ is the unit outer norm vector on $\partial \Omega_1$.

Results by Li, Rosencrans, Zhang and Wang¹

- Suppose $a_{ij}(x) = \sigma(\overline{a}_{ij}(x))$ with $\overline{a}_{ij}(x) \in C^1(\overline{\Omega}_2)$ and $\sigma(\delta)$ is a positive parameter.
- If σ is bounded and $\lim_{\delta \to 0} \frac{\sigma}{\delta} = \alpha$, then $u \to v$ in $L^2(\Omega_1 \times [0,T])$, where v is the weak solution of

$$\begin{cases} v_t - k\Delta v = f(x,t), & (x,t) \in Q_T, \\ k\frac{\partial v}{\partial \mathbf{n}} + \alpha(\sum_{i,j} \overline{a}_{ij}(x)n_in_j)v = 0, & (x,t) \in S_T, \\ v = u_0, & x \in \Omega, t = 0 \end{cases}$$
(3)

• A nature question : what is the effective boundary condition if $\sigma \to \infty$ as $\delta \to 0$?

 1. J. Li, S. Rosencrans, K. Zhang, and X. Wang, 2009, Proc AMS

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 Effective boundary conditions

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Interior Inclusion in 3D



Figure.1: $\Omega = \overline{\Omega}_1 \cup \overline{\Omega}_\delta \cup \Omega_2$.

Let

$$A(x) = \begin{cases} k_1, & x \in \Omega_1 \\ (a_{ij})_{3 \times 3}, & x \in \Omega_\delta \\ k_2, & x \in \Omega_2 \end{cases}$$

where k_1 and k_2 are two positive constants independent of $\delta > 0$; σ is a positive function of δ ; Ω and Ω_1 are fixed with $\Gamma_1 \in C^2$.

Optimally aligned condition



Optimally aligned coating²: for any $x \in \Omega_{\delta}$, $\mathbf{n}(p)$ is always an eigenvector. In the curvilinear coordinates (s, r), $x = p + r\mathbf{n}(p) \in \Omega_{\delta}$, suppose

$$A(x)\mathbf{n}(p) = \sigma \mathbf{n}(p), \quad A(x)\mathbf{s}(p) = \mu \mathbf{s}(p), \tag{4}$$

where \mathbf{p} - the projection of x on $\Gamma_1 = \partial \Omega_1$; r- distance from x to Γ_1 ; $\mathbf{s}(p)$ is an arbitrary tangent vector at p on $\partial \Omega_1$.

$$W_{2}^{1,0}(Q_T) = \{ u \in L^2(Q_T) : \nabla u \in L^2(Q_T) \};$$

$$W_{2,0}^{1,0}(Q_T) = \{ u \in W_2^{1,0}(Q_T) : \text{ with trace } 0 \text{ on} S_T \};$$

$$W_2^{1,1}(Q_T) = \{ u \in L^2(Q_T) : u_t, \nabla u \in L^2(Q_T) \};$$

$$W_{2,0}^{1,1}(Q_T) = \{ u \in W_2^{1,1}(Q_T) : \text{ with trace } 0 \text{ on} S_T \};$$

$$V_2^{1,0}(Q_T) = \{ u \in W_2^{1,0}(Q_T) : u \in C([0,T], L^2(\Omega)) \};$$

$$V_{2,0}^{1,0}(Q_T) = \{ u \in V_2^{1,0}(Q_T) : \text{ with trace } 0 \text{ on} S_T \};$$

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Definition

u is a weak solution of (1), if $u(x,t) \in V_{2,0}^{1,0}(Q_T)$ and it holds that

$$\mathcal{A}[u,\xi] = -\int_{\Omega} u_0(x)\xi(x,0)dx + \int_{Q_T} (A(x)\nabla u) \cdot \nabla\xi - u\xi_t - f\xi dtdx \qquad (5)$$
$$=0$$

for any $\xi \in W_{2,0}^{1,1}(Q_T)$ satisfying $\xi = 0$ at t = T,

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Lemma

$$(i) \max_{t \in [0,T]} \int_{\Omega} u^{2}(x,t) dx + \int_{Q_{T}} \nabla u \cdot A(x) \nabla u dx dt$$

$$\leq C(T) (\int_{\Omega} u_{0}^{2} dx + \int_{Q_{T}} f^{2} dx dt);$$

$$(ii) \max_{t \in [0,T]} t \int_{\Omega} \nabla u \cdot A(x) \nabla u(x,t) dx + \int_{Q_{T}} t u_{t}^{2} dx dt$$

$$\leq C(T) (\int_{\Omega} u_{0}^{2} dx + \int_{Q_{T}} f^{2} dx dt).$$

$$(6)$$

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Lemma (2)

Suppose $\Gamma_1 \in C^3$ and $f \in L^2(Q_T)$ with $u_0 \in L^2(\Omega)$. Then, for any fixed $t_0 > 0$, the weak solution u of (1) satisfies the following inequalities :

$$\int_{t_0}^T \int_{\Omega_{\delta}} \mu(\Delta_{\Gamma} u)^2 + \sigma(\nabla_{\Gamma} u_r)^2 \le O(1) + O(\frac{\sigma}{\mu}) + O(\frac{1}{\mu}) \tag{7}$$

and

$$\int_{t_0}^T \int_{\Omega_\delta} \sigma u_{rr}^2 \le O(1) + O(\frac{1}{\sigma}) + O(\frac{\mu}{\sigma}) \tag{8}$$

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Theorem (X.Chen, C.Pond and X.Wang)

Let $m \geq 2$ be an integer and $\alpha \in (0, 1)$. Suppose that $\partial \Omega_1 \in C^{m+\alpha}$ and $f \in C^{m-2+\alpha,(m-2+\alpha)/2}(\overline{\Omega}_h \times [0,T])(h=1,\delta,2)$, and $a_{ij} \in C^{m-1+\alpha,(m-1+\alpha)/2}(\overline{\Omega}_h \times [0,T])$, then for any $t_0 > 0$, the weak solution u of (1) satisfies

$$u \in C^{m+\alpha,(m+\alpha)/2}(\overline{\mathcal{N}}_h \times [t_0,T])$$

where \mathcal{N} is a narrow neighborhood of $\partial \Omega_1$ and $\mathcal{N}_h = \mathcal{N} \cap \Omega_h$.

 3. X.Chen, C.Pond and X.Wang, Arch.Ration.Mech.Anal.(2012)

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 Effective boundary conditions
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Main results

Theorem (Geng)

^a Denote $A_0(x) = k_1, x \in \Omega_1$ and $A_0 = k_2, x \in \Omega \setminus \overline{\Omega}_1$. Suppose $\Gamma_1 \in C^3$

$$\lim_{\delta \to 0} \frac{\sigma}{\delta} = b \in [0, \infty], \quad \lim_{\delta \to 0} \sigma \delta = a \in [0, \infty],$$

$$\lim_{\delta \to 0} \sigma \mu = \gamma \in [0, \infty], \quad \lim_{\delta \to 0} \mu \delta = \beta \in [0, \infty].$$
(9)

As $\delta \to 0$, $u \to v$ strongly in $C([0,T]; L^2(\Omega))$, where v is the weak solution of

$$\begin{cases} v_t - \nabla \cdot (A_0(x)\nabla v) = f(x,t), & (x,t) \in Q_T, \\ v = 0, & (x,t) \in S_T, \\ v = u_0, & x \in \Omega, t = 0, \end{cases}$$
(10)

subject to the effective boundary conditions on $\Gamma_1\times(0,T)$:

a. Xingri Geng, submitted

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Main results

Theorem (Geng)

Case 1. $\frac{\sigma}{\delta} \to 0$ as $\delta \to 0$.			
As $\delta \to 0$	$\gamma = 0$	$\gamma \in (0, \infty)$	$\gamma = \infty$
$\beta = 0$	$ \begin{array}{c c} k_1 \frac{\partial v_1}{\partial \mathbf{n}} = 0, \\ k_1 \frac{\partial v_1}{\partial \mathbf{n}} = k_2 \frac{\partial v}{\partial \mathbf{n}} \end{array} $	2	
$\beta \in (0,\infty)$	$ \begin{array}{c} k_1 \frac{\partial v_1}{\partial \mathbf{n}} = 0, \\ k_1 \frac{\partial v_1}{\partial \mathbf{n}} = k_2 \frac{\partial v}{\partial \mathbf{n}} \end{array} $	2	
$\beta = \infty$	$ \begin{array}{c} k_1 \frac{\partial v_1}{\partial \mathbf{n}} = 0, \\ k_1 \frac{\partial v_1}{\partial \mathbf{n}} = k_2 \frac{\partial v}{\partial \mathbf{r}} \end{array} $	$\begin{aligned} k_1 \frac{\partial v_1}{\partial \mathbf{n}} &= \gamma \mathcal{J}_1^\infty[v_1],\\ k_2 \frac{\partial v_2}{\partial \mathbf{n}} &= -\gamma \mathcal{J}_1^\infty[v_2] \end{aligned}$	$\nabla_{\Gamma_1} v_1 = \nabla_{\Gamma_1} v_2 = 0, \int_{\Gamma_1} \frac{\partial v_1}{\partial \mathbf{n}} = 0, \int_{\Gamma_1} \left(k_1 \frac{\partial v_1}{\partial \mathbf{n}} - k_2 \frac{\partial v_2}{\partial \mathbf{n}} \right) = 0$
	С	ase 2. $\frac{\sigma}{\delta} \rightarrow b \in (0, \infty)$ as	$\delta \rightarrow 0.$
As $\delta \to 0$	$\gamma = 0$	$\gamma \in (0, \infty)$	$\gamma = \infty$
$\beta = 0$	$ \begin{aligned} & k_1 \frac{\partial v_1}{\partial \mathbf{n}} \\ &= k_2 \frac{\partial v_2}{\partial \mathbf{n}}, \\ & k_1 \frac{\partial v_1}{\partial \mathbf{n}} \\ &= b(v_2 - v_1) \end{aligned} $		
$\beta\in (0,\infty)$		$\begin{array}{l} k_1 \frac{\partial v_1}{\partial \mathbf{n}} = \\ \gamma \mathcal{J}_1^{\beta/\gamma}[v_1] - \gamma \mathcal{J}_2^{\beta/\gamma}[v_2], \\ k_2 \frac{\partial v_2}{\partial \mathbf{n}} = \\ \gamma \mathcal{J}_2^{\beta/\gamma}[v_1] - \gamma \mathcal{J}_1^{\beta/\gamma}[v_2] \end{array}$	
$\beta = \infty$			$ \begin{aligned} \nabla_{\Gamma_1} v_1 &= \nabla_{\Gamma_1} v_2 \\ &= 0, \\ \int_{\Gamma_1} \left(k_1 \frac{\partial v_1}{\partial \mathbf{n}} - k_2 \frac{\partial v_2}{\partial \mathbf{n}} \right) \\ &= 0, \\ \int_{\Gamma_1} \left(k_1 \frac{\partial v_1}{\partial \mathbf{n}} - b(v_2 - v_1) \right) \\ &= 0 \end{aligned} $

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Effective boundary conditions

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Theorem (Geng)

Case 3. $\frac{\sigma}{\delta} \to \infty$ and $\sigma \delta^3 \to 0$ as $\delta \to 0$.			
As $\delta \to 0$	$\gamma = 0$	$\gamma \in (0,\infty)$	$\gamma = \infty$
eta=0	$v_1 = v_2, \ k_1 rac{\partial v_1}{\partial \mathbf{n}} = k_2 rac{\partial v_2}{\partial \mathbf{n}}$	$v_1 = v_2, k_1 rac{\partial v_1}{\partial \mathbf{n}} = k_2 rac{\partial v_2}{\partial \mathbf{n}}$	$v_1 = v_2, \ k_1 rac{\partial v_1}{\partial \mathbf{n}} = k_2 rac{\partial v_2}{\partial \mathbf{n}}$
$\beta \in (0,\infty)$			$v_1 = v_2, \ k_1 rac{\partial v_1}{\partial \mathbf{n}} - k_2 rac{\partial v_2}{\partial \mathbf{n}} = eta \Delta_{\Gamma_1} v$
$\beta = \infty$			$egin{aligned} v_1 &= v_2, \ abla &= 0, \ &\int_{\Gamma_1} \left(k_1 rac{\partial v_1}{\partial \mathbf{n}} - k_2 rac{\partial v_2}{\partial \mathbf{n}} ight) = 0 \end{aligned}$

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Remarks :

- $\sigma \delta^3 \to 0$ can be removed if $\frac{\mu}{\sigma}$ does not vanish as $\delta \to 0$;
- $\nabla_{\Gamma_1} v = 0$ means v is a constant in x but may depend on t;
- Δ_{Γ_1} is the Laplacian-Beltrami;
- \mathcal{J}^H is called Dirichlet-to-Neumann map;
- Lots of new and exotic EBCs emerge, including the fractional Laplacian-Beltrami and the Dirichlet-to-Neumann mapping.

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Let g(s) be a function on $\partial \Omega_1$ and Ψ is defined by

$$\begin{cases} \Psi_{RR} + \Delta_{\Gamma} \Psi = 0, & \partial \Omega_1 \times (0, H), \\ \Psi(s, 0) = g(s), & \Psi(s, H) = g(s). \end{cases}$$
(11)

Moreover,

$$\mathcal{J}^H[g] := \Psi_R(s, 0), \tag{12}$$

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where \mathcal{J}^H is symmetric for $H \in (0, \infty)$ and

$$\mathcal{J}^{\infty} = \lim_{H \to \infty} \mathcal{J}^{H} = -(-\Delta_{\Gamma_1})^{1/2}.$$
 (13)

 \mathcal{J}^H can be given in eigenfunctions of the Laplace-Beltrami operator.

Theorem (Isotropic case)

(i) If $\lim_{\delta \to 0} \frac{\sigma}{\delta} = b \in [0, \infty]$ and $\sigma \to 0$, then

$$k_1 \frac{\partial v_1}{\partial \boldsymbol{n}} = b(v_1 - v_2), \quad k_1 \frac{\partial v_1}{\partial \boldsymbol{n}} = k_2 \frac{\partial v_2}{\partial \boldsymbol{n}}.$$

(ii) If $\lim_{\delta \to 0} \sigma \delta = a \in [0, \infty)$ and $\sigma \ge O(1) > 0$, then

$$v_1 = v_2, \quad k_1 \frac{\partial v_1}{\partial \boldsymbol{n}} - k_2 \frac{\partial v_2}{\partial \boldsymbol{n}} = a \Delta_{\Gamma_1} v$$

(iii) If $\lim_{\delta \to 0} \sigma \delta = \infty$, then

$$v_1 = v_2, \quad \nabla_{\Gamma_1} v = 0, \quad \int_{\Gamma_1} (k_1 \frac{\partial v_1}{\partial n} - k_2 \frac{\partial v_2}{\partial n}) ds = 0,$$

where v_1 and v_2 are the restrictions of v on $\Omega_1 \times (0,T)$ and $(\Omega \setminus \Omega_1) \times (0,T)$, respectively.

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Main Steps :

- Step 1 : existence and uniqueness of weak solution of (1);
- Step 2 : energy estimates of the weak solution of (1) and prove $u \to v$ strongly in $C([0,T]; L^2(\Omega))$ as $\delta \to 0$;
- Step 3 : show that v is the exact weak solution of (10) with related EBCs;
 - Construct a test function such that $\overline{\xi}(s, r, t) = \psi(s, r, t)$ in Ω_{δ} ,

$$\begin{cases} \sigma \psi_{rr} + \mu \Delta_{\Gamma} \psi = 0, & \Gamma_1 \times (0, \delta), \\ \psi(s, 0, t) = g_1(s) & \psi(s, \delta, t) = g_2(s) \end{cases}$$
(14)

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- By rescaling, $\Psi(s,R)=\psi(s,\sqrt{\mu/\sigma}r,t)$
- Step 4 : existence and uniqueness of the weak solution of the effective equation (10) with related EBCs;

Boundary layers Two identical tangent thermal conductivity



Fig. 1. The domain $\Omega = \overline{\Omega}_1 \cup \Omega_2 \subset \mathbb{R}^N$ consists of an isotropic body Ω_1 surrounded by a layer Ω_2 of uniform thickness δ

Theorem (Boundary case)

^a Suppose A(x) is given by (4). If u is the weak solution of (1), then as $\delta \to 0$, $u \to v$ strongly in $C([0,T]; L^2(\Omega))$, where v is the weak solution of the effective equation :

$$\begin{cases} v_t - k\Delta v = f(x, t), & (x, t) \in \Omega_1 \times (0, T), \\ v(x, 0) = u_0, & x \in \partial \Omega_1, \end{cases}$$
(15)

a. Xingri Geng, Submitted

Theorem (Boundary case)

subject to the following effective boundary conditions :

As $\delta \to 0$	$\frac{\sigma}{\delta} \to 0$	$\frac{\sigma}{\delta} \to \alpha \in (0,\infty)$	$rac{\sigma}{\delta} o \infty$
$\sigma\mu \rightarrow 0$	$\frac{\partial v}{\partial \mathbf{n}} = 0$	$k \frac{\partial v}{\partial \mathbf{n}} = -\alpha v$	v = 0
$\overline{\sqrt{\sigma\mu} \to \gamma \in (0,\infty)}$	$k \frac{\partial v}{\partial \mathbf{n}} = \gamma \mathcal{J}_D^\infty[v]$	$k \frac{\partial v}{\partial \mathbf{n}} = \gamma \mathcal{J}_D^{\gamma/lpha}[v]$	v = 0
$\sigma\mu ightarrow\infty$	$ abla_{\Gamma} v = 0, \ \int_{\partial\Omega_1} rac{\partial v}{\partial \mathbf{n}} = 0$	$ abla_{\Gamma}v=0,\ \int_{\partial\Omega_1}(krac{\partial v}{\partial {f n}}+lpha v)dx=0$	v = 0

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Assume $\partial \Omega_1$ is a topological torus, namely, $\partial \Omega_1 = \Gamma_1 \times \Gamma_2$, and A(x) satisfies

$$A(x)\mathbf{n}(p) = \sigma \mathbf{n}(p),$$

$$A(x)\mathbf{t}_1(p) = \mu_1 \mathbf{t}_1(p),$$

$$A(x)\mathbf{t}_2(p) = \mu_2 \mathbf{t}_2(p),$$

(16)

where $\mathbf{t}_1, \mathbf{t}_2$ are two orthonormal eigenvectors of A(x) in the tangent plane. WOLG, suppose $\mu_1 > \mu_2$ and $\frac{\mu_2}{\mu_1} \to c \in [0, 1]$.

• If $c \in (0, 1]$, EBCs are similar as above;

• If
$$c = 0$$
 with $\frac{\mu_2/\mu_1}{\delta^2} \to 0$, new results arise.

As $\delta \to 0$	$\frac{\sigma}{\delta} \rightarrow 0$	$\frac{\sigma}{\delta} \to \alpha \in (0,\infty)$	$rac{\sigma}{\delta} ightarrow \infty$
$\sigma\mu_1 o 0$	$\frac{\partial v}{\partial \mathbf{n}} = 0$	$k \frac{\partial v}{\partial \mathbf{n}} = -\alpha v$	v = 0
$\sqrt{\sigma\mu_1} o \gamma_1 \in (0,\infty)$	$k \frac{\partial v}{\partial \mathbf{n}} = \gamma_1 \mathcal{K}_D^\infty[v]$	$krac{\partial v}{\partial \mathbf{n}}=\gamma_1\mathcal{K}_D^{\gamma_1/lpha}[v]$	v = 0
$\sigma\mu_1 ightarrow \infty$	$\overline{ abla_{\Gamma}v=0},\ \int_{\Gamma}rac{\partial v}{\partial \mathbf{n}}=0$	$ abla_{\Gamma} v = 0, \ \int_{\Gamma} (k rac{\partial v}{\partial \mathbf{n}} + lpha v) = 0$	v = 0

Figure – EBCs on $\partial \Omega_1$ for $c \neq 0$

As $\delta \to 0$	$\frac{\sigma}{\delta} \rightarrow 0$	$\frac{\sigma}{\delta} \to \alpha \in (0,\infty)$	$\frac{\sigma}{\delta} \to \infty$
$\sigma \mu_1 \rightarrow 0$	$\frac{\partial v}{\partial \mathbf{n}} = 0$	$k \frac{\partial v}{\partial \mathbf{n}} = -\alpha v$	v = 0
$\sqrt{\sigma\mu_1} o \gamma_1 \in (0,\infty)$	$k rac{\partial v}{\partial \mathbf{n}} = \gamma_1 \Lambda_D^\infty[v]$	$krac{\partial v}{\partial \mathbf{n}}=\gamma_1\Lambda_D^{\gamma_1/lpha}[v]$	v = 0
$\sigma\mu_1 ightarrow \infty, \sigma\mu_2 ightarrow 0$	$rac{\partial v}{\partial au_1} = 0, \ \int_{\Gamma_1} rac{\partial v}{\partial \mathbf{n}} = 0$	$rac{\partial v}{\partial au_1} = 0, \ \int_{\Gamma_1} ig(rac{\partial v}{\partial \mathbf{n}} + lpha vig) = 0$	v = 0
$ \begin{aligned} \sigma \mu_1 \to \infty, \\ \sqrt{\sigma \mu_2} \to \gamma_2 \in (0,\infty) \end{aligned} $	$rac{\partial v}{\partial au_1} = 0, \ \int_{\Gamma_1} \left(k rac{\partial v}{\partial \mathbf{n}} - \gamma_2 \mathcal{D}_D^\infty[v] ight) = 0$	$rac{\partial v}{\partial au_1} = 0, \ \int_{\Gamma_1} \left(k rac{\partial v}{\partial \mathbf{n}} - \gamma_2 \mathcal{D}_D^{\gamma_2/lpha}[v] ight) = 0$	v = 0
$\sigma\mu_1 o \infty, \sigma\mu_2 o \infty$	$ abla_{\Gamma} v = 0, \ \int_{\Gamma} rac{\partial v}{\partial \mathbf{n}} = 0$	$ abla_{\Gamma} v = 0, \ \int_{\Gamma} rac{\partial v}{\partial \mathbf{n}} = 0$	v = 0

Figure – EBCs on $\partial \Omega_1$ for c = 0

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For $H \in (0, \infty)$, $\Lambda_D^H[g] := \Phi_R(s, 0)$ and $\Lambda_D^\infty := \lim_{H \to \infty} \Lambda_D^H$, where $\Phi(s, R)$ is the bounded solution of

$$\begin{cases} \Phi_{RR} + \Phi_{s_1 s_1} = 0, & \partial \Omega_1 \times (0, H), \\ \Phi(s, 0) = g(s), & \Phi(s, H) = 0. \end{cases}$$
(17)

Moreover, $\mathcal{D}_D^H[g] := \Psi_R(s_2, 0)$ and $\mathcal{D}_D^\infty := \lim_{H \to \infty} \mathcal{D}_D^H$, where $\Psi(s_2, R)$ is the bounded solution of

$$\begin{cases} \Psi_{RR} + \Psi_{s_2 s_2} = 0, \quad \Gamma_2 \times (0, H), \\ \Psi(s_2, 0) = g(s_2), \quad \Psi(s_2, H) = 0. \end{cases}$$
(18)

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• Use the idea of EBCs to derive new model for other nonlinear equations such as the Fisher-KPP equation and reaction diffusion systems.

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THANK YOU!

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Effective boundary conditions

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